

# N-body Interaction Simulations I

## Learning Physics from the Sky Down

- Discovering phenomenology from simulations
- Using fundamentals to build models
- Coding algorithms to build simulations from models

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# Introduction to this Session ( I )

Demonstration (GalaxSee):  
a simulated N-body gravitating system.

- What can be learned?
  - \* Extreme example of Newton's law of gravitation
  - \* Basic physics, interplay between gravitational binding and angular momentum
  - \* Slightly more advanced, interplay between kinetic energy and gravitational binding (Virial Theorem)
  - \* Scaling of N-body style (action at a distance) problems
  - \* Unit systems and normalization

Does gravity need an N-body model?

- Why is an electromagnetic system different?
  - \* Action at a distance is different when charges cancel
  - \* Complicated electromagnetic systems (i.e. macromolecules solvated in polar solvents) may still have significant action at a distance for key problems.

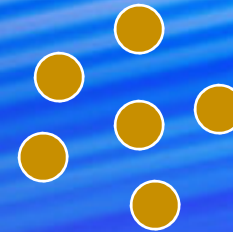
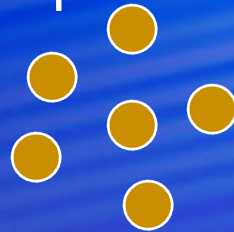
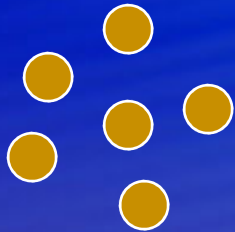
# Direct Force Calculation

## Algorithm

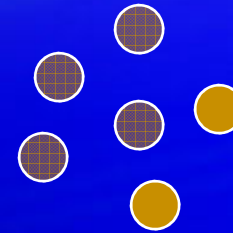
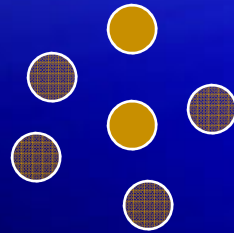
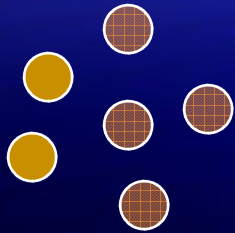
- Given its velocity, what is displacement for each object in this domain?
- Given their new positions, **WHAT IS THE RESULTANT FORCE** on each from all the other objects?
- What is the change in velocity of each object due to the net force on it?

# Parallelization

Everyone steps all bodies



But forces are calculated across processes



# Parallelization in the Direct Force Algorithm

The steps needed for each calculation:

- Single Instruction – Multiple Data
  - \* Each process integrates every particle
  - \* Each process calculates some of the accelerations
  - \* Each process shares acceleration information

The point of diminishing returns:

- The more you split up the problem, the less work each processor does, thus the ratio of concurrent work to redundant work and communication reduces.

# Amdahl's Law and optimal efficiency:

- General Law

- Best case time =  
A CONCURRENT/P + B REDUNDANT
- Speedup approaches a limit

- N-body is worse:

- $\text{time} = (a \cdot N^2 / P) + (b \cdot N \cdot P) + (c \cdot N) + (d \cdot P)$
- Speedup falls off as  $1/P$  for large  $P$  (time increases linearly)
- Large  $N$ , less communication can increase the value of  $P$  before speedup falls off.

# Gathering Performance Data

Logging onto a cluster:

Running GalaxSee on a cluster:

Gathering run time data:

- See handout

# Prelude to N-Body II

Where is the most computation-intensive part of the calculations in GalaxSee?

- Force calculation, not the kinematic calculation.

Scalability issues:

- We must reduce the number of steps in this part, as dependent upon  $N$  - the number of objects.